




Evidence in favor of a scientific theory
With great complexity comes great honesty

Gustavo Landfried

@GALandfried 

MSc in Anthropological Sciences
PhD student in Computer Sciences



DEPARTAMENTO
DE COMPUTACION

Facultad de Ciencias Exactas y Naturales - UBA

Why Bayesian inference?

Allows us to optimally update a priori beliefs given a model and data.

Where comes from?

	Not infected	Infected	
Not vaccinated	4	2	6
Vaccinated	76	18	94
	80	20	100

From conditional probability

Where comes from?

	Not infected	Infected	
Not vaccinated	4	2	6
Vaccinated	76	18	94
	80	20	100

From conditional probability

$$P(\text{Not infected}|\text{Vaccinated}) = \frac{P(\text{Vaccinated} \cap \text{Not infected})}{P(\text{Vaccinated})}$$

Where comes from?

	Not infected	Infected	
Not vaccinated	4	2	6
Vaccinated	76	18	94
	80	20	100

From conditional probability

$$P(\text{Not infected}|\text{Vaccinated}) = \frac{P(\text{Vaccinated} \cap \text{Not infected})}{P(\text{Vaccinated})}$$

Bayes theorem:

$$P(A_1|B_1) = \frac{P(B_1 \cap A_1)}{P(B_1)} = \frac{P(B_1|A_1)P(A_1)}{P(B_1)} \quad (1)$$

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

One percent of the time it incorrectly detect normal persons as zombies.

- $P(\text{positive}|\text{mortal}) = 0.01$

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

One percent of the time it incorrectly detect normal persons as zombies.

- $P(\text{positive}|\text{mortal}) = 0.01$

We know that zombies are only 0.1% of the population.

- $P(\text{zombie}) = 0.001$

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

One percent of the time it incorrectly detect normal persons as zombies.

- $P(\text{positive}|\text{mortal}) = 0.01$

We know that zombies are only 0.1% of the population.

- $P(\text{zombie}) = 0.001$

Someone receive a positive test:

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

One percent of the time it incorrectly detect normal persons as zombies.

- $P(\text{positive}|\text{mortal}) = 0.01$

We know that zombies are only 0.1% of the population.

- $P(\text{zombie}) = 0.001$

Someone receive a positive test:

She has **only 8.7% chance** to actually be a zombie!

$$P(\text{zombie}|\text{positive}) = \frac{P(\text{positive}|\text{zombie})P(\text{zombie})}{P(\text{positive})}$$

Scientific test example

There is a test that correctly detects zombies 95% of the time.

- $P(\text{positive}|\text{zombie}) = 0.95$

One percent of the time it incorrectly detect normal persons as zombies.

- $P(\text{positive}|\text{mortal}) = 0.01$

We know that zombies are only 0.1% of the population.

- $P(\text{zombie}) = 0.001$

Someone receive a positive test:

She has **only 8.7% chance** to actually be a zombie!?

$$P(\text{zombie}|\text{positive}) = \frac{P(\text{positive}|\text{zombie})P(\text{zombie})}{P(\text{positive})}$$

In this example all frequencies were observables

The inferential jump

Bayesian inference is about hidden variables

About our **belief distributions** of those hidden variables!

The inferential jump

Bayesian inference is about hidden variables

About our **belief distributions** of those hidden variables!

$$\underbrace{P(\text{Belief}|\text{Data})}_{\text{Posterior}} = \frac{\overbrace{P(\text{Data}|\text{Belief})}^{\text{Likelihood}} \overbrace{P(\text{Belief})}^{\text{Prior}}}{\underbrace{P(\text{Data})}_{\text{Evidence or Average likelihood}}}$$

The inferential jump

Bayesian inference is about hidden variables

About our **belief distributions** of those hidden variables!

$$\underbrace{P(\text{Belief}|\text{Data})}_{\text{Posterior}} = \frac{\overbrace{P(\text{Data}|\text{Belief})}^{\text{Likelihood}} \overbrace{P(\text{Belief})}^{\text{Prior}}}{\underbrace{P(\text{Data})}_{\text{Evidence or Average likelihood}}}$$

A model is always there!

$$\underbrace{P(\text{Belief}|\text{Data}, \text{Model})}_{\text{Posterior}} = \frac{\overbrace{P(\text{Data}|\text{Belief}, \text{Model})}^{\text{Likelihood}} \overbrace{P(\text{Belief}|\text{Model})}^{\text{Prior}}}{\underbrace{P(\text{Data}|\text{Model})}_{\text{Evidence or Average likelihood}}}$$

- **Prior** belief (distribution):

$$P(B|M) = \frac{1}{\#\text{Beliefs}} \quad \forall B \in \text{Beliefs}$$

- **Prior** belief (distribution):

$$P(B|M) = \frac{1}{\#\text{Beliefs}} \quad \forall B \in \text{Beliefs}$$

- **Likelihood** or ways in which data may have been generated (distribution):

$$P(D|B, M) = \frac{\text{Ways to produce } D \text{ given } B \text{ and } M}{\text{Total ways given } B \text{ and } M} \quad \forall B \in \text{Beliefs}$$

- **Prior** belief (distribution):

$$P(B|M) = \frac{1}{\#\text{Beliefs}} \quad \forall B \in \text{Beliefs}$$

- **Likelihood** or ways in which data may have been generated (distribution):

$$P(D|B, M) = \frac{\text{Ways to produce } D \text{ given } B \text{ and } M}{\text{Total ways given } B \text{ and } M} \quad \forall B \in \text{Beliefs}$$

- **Evidence** or Average likelihood (scalar):

$$P(D|M) = \sum_{B \in \text{Beliefs}} \underbrace{P(D|B, M)}_{\text{likelihood}} \underbrace{P(B|M)}_{\text{prior}}$$

- **Prior** belief (distribution):

$$P(B|M) = \frac{1}{\#\text{Beliefs}} \quad \forall B \in \text{Beliefs}$$

- **Likelihood** or ways in which data may have been generated (distribution):

$$P(D|B, M) = \frac{\text{Ways to produce } D \text{ given } B \text{ and } M}{\text{Total ways given } B \text{ and } M} \quad \forall B \in \text{Beliefs}$$

- **Evidence** or Average likelihood (scalar):

$$P(D|M) = \sum_{B \in \text{Beliefs}} \underbrace{P(D|B, M)}_{\text{likelihood}} \underbrace{P(B|M)}_{\text{prior}}$$

- **Posterior** belief (distribution):

$$P(B|D, M) = \frac{P(D|B, M)P(B|M)}{P(D|M)} \quad \forall B \in \text{Beliefs}$$

The garden of forking paths

To update our beliefs (posterior), we need to consider every possible path in the model that could have lead us to the observed data (likelihood).

The garden of forking paths

Data (D): ● ○ ●

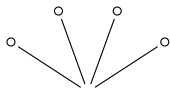
Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)

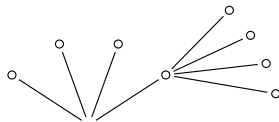


Ways given M and $B = \text{○○○○}$ (First marbel)

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)

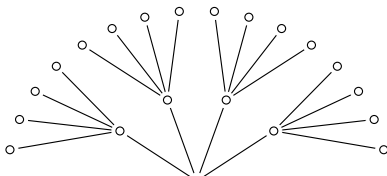


Ways given M and $B = \text{○○○○}$ (Second marble)

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)

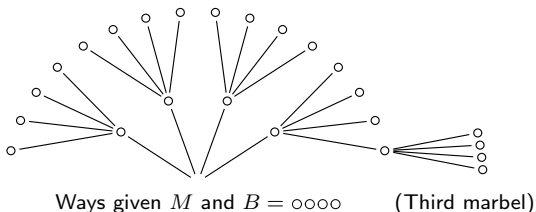


Ways given M and $B = \text{○○○○}$ (Second marble)

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

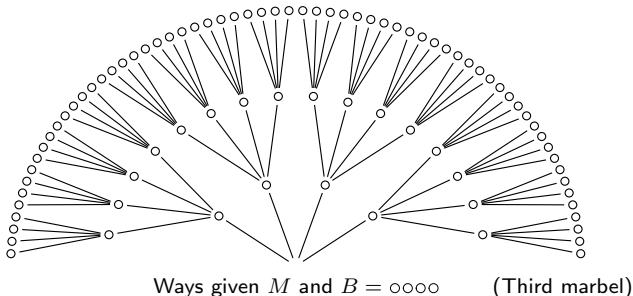
Model (M): Data \sim Binomial(n, p)



The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○ ○ ○ ○, ● ○ ○ ○, ● ● ○ ○, ● ● ● ○, ● ● ● ●

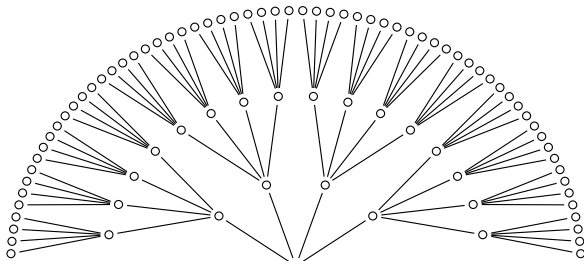
Model (M): Data \sim Binomial(n, p)



The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○ ○ ○ ○, ● ○ ○ ○, ● ● ○ ○, ● ● ● ○, ● ● ● ●

Model (M): Data \sim Binomial(n, p)



Ways given M and $B = \text{○ ○ ○ ○}$

Belief

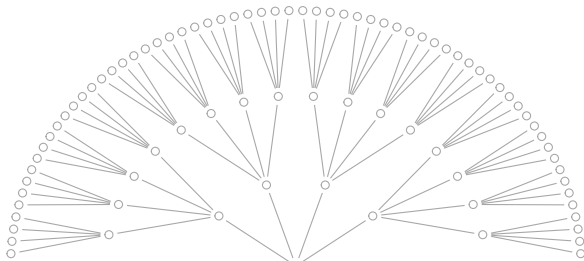
Ways to produce ● ○ ●

○ ○ ○ ○

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○ ○ ○ ○, ● ○ ○ ○, ● ● ○ ○, ● ● ● ○, ● ● ● ●

Model (M): Data \sim Binomial(n, p)



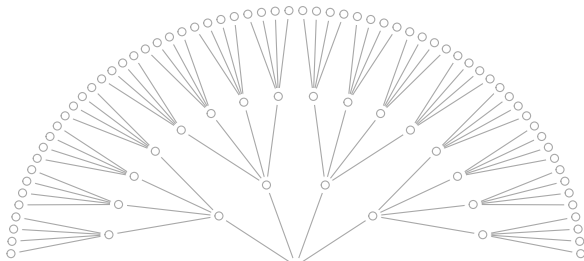
Ways given M and $B = \text{○ ○ ○ ○}$

Belief	Ways to produce ● ○ ●
○ ○ ○ ○	$0 \times 4 \times 0 = 0$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



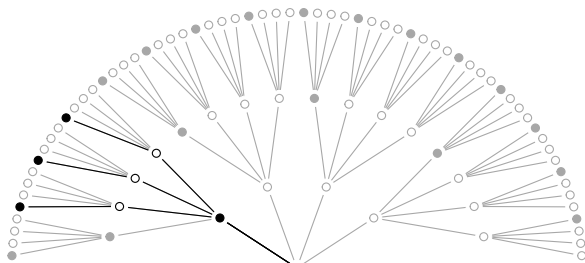
Ways given M and $B = \text{○○○○}$

Belief	Ways to produce ● ○ ●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	$1/5$	$\frac{0}{64} \frac{1}{5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



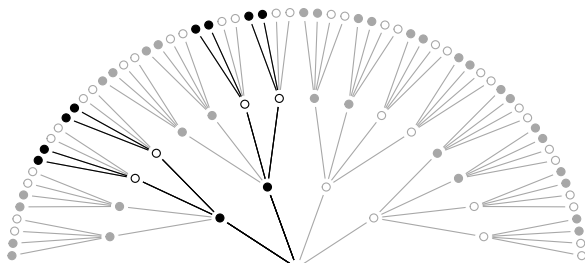
Ways given M and $B = ●○○○$

Belief	Ways to produce ●○○●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	$\frac{3}{64}$	1/5	$\frac{3}{64} \frac{1}{5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○ ○ ○ ○, ● ○ ○ ○, ● ● ○ ○, ● ● ● ○, ● ● ● ●

Model (M): Data \sim Binomial(n, p)



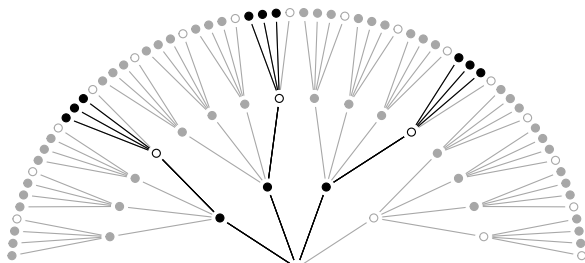
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ● ○ ●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



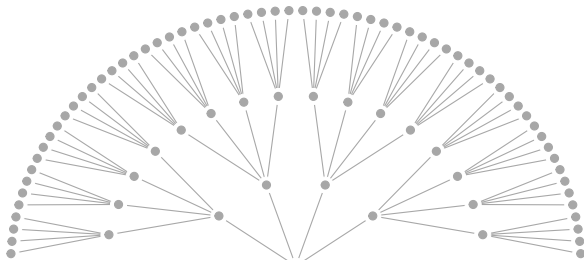
Ways given M and $B = \bullet\bullet\bullet\circ$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



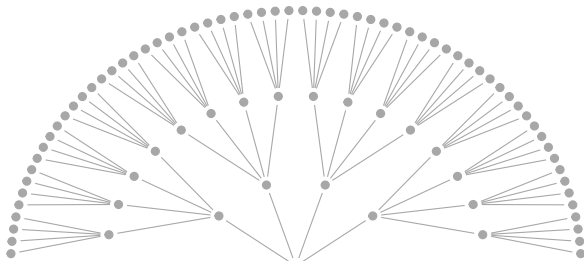
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



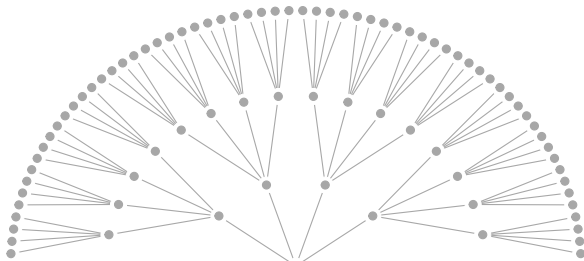
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$
				$P(D M)$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



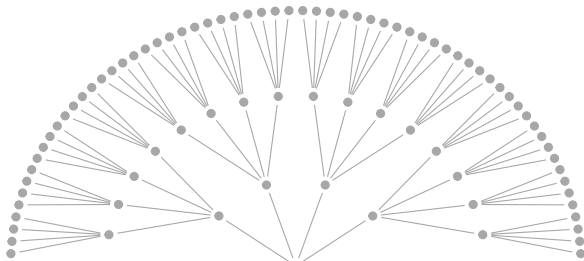
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$
				$\frac{3+8+9}{64 \cdot 5}$

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



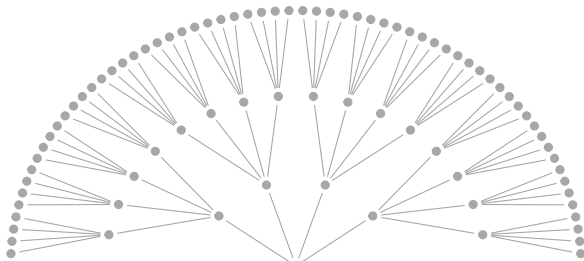
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto	Posterior
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$	$\frac{0}{64} \frac{1}{5} \frac{64 \cdot 5}{3+8+9}$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$	
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$	
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$	
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$	
				$\frac{3+8+9}{64 \cdot 5}$	

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



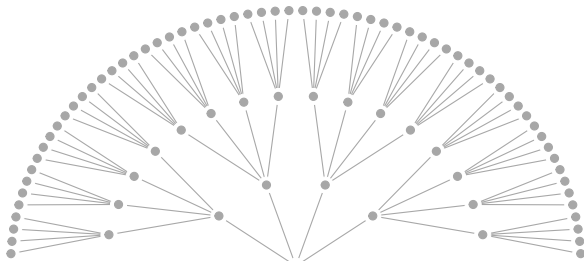
Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ● ○ ●	Likelihood	Prior	Posterior \propto	Posterior
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$	$\frac{0}{3+8+9} = 0.00$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$	
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$	
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$	
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$	
				$\frac{3+8+9}{64 \cdot 5}$	

The garden of forking paths

Data (D): ● ○ ● Beliefs (B): ○○○○, ●○○○, ●●○○, ●●●○, ●●●●

Model (M): Data \sim Binomial(n, p)



Ways given M and $B = \bullet\bullet\bullet\bullet$

Belief	Ways to produce ●○●	Likelihood	Prior	Posterior \propto	Posterior
○○○○	$0 \times 4 \times 0 = 0$	$\frac{0 \times 4 \times 0}{4 \times 4 \times 4} = \frac{0}{64}$	1/5	$\frac{0}{64} \frac{1}{5}$	$\frac{0}{3+8+9} = 0.00$
●○○○	$1 \times 3 \times 1 = 3$	3/64	1/5	$\frac{3}{64} \frac{1}{5}$	$\frac{3}{3+8+9} = 0.15$
●●○○	$2 \times 2 \times 2 = 8$	8/64	1/5	$\frac{8}{64} \frac{1}{5}$	$\frac{8}{3+8+9} = 0.40$
●●●○	$3 \times 1 \times 3 = 9$	9/64	1/5	$\frac{9}{64} \frac{1}{5}$	$\frac{9}{3+8+9} = 0.45$
●●●●	$4 \times 0 \times 4 = 0$	0/64	1/5	$\frac{0}{64} \frac{1}{5}$	$\frac{0}{3+8+9} = 0.00$
				$\frac{3+8+9}{64 \cdot 5}$	

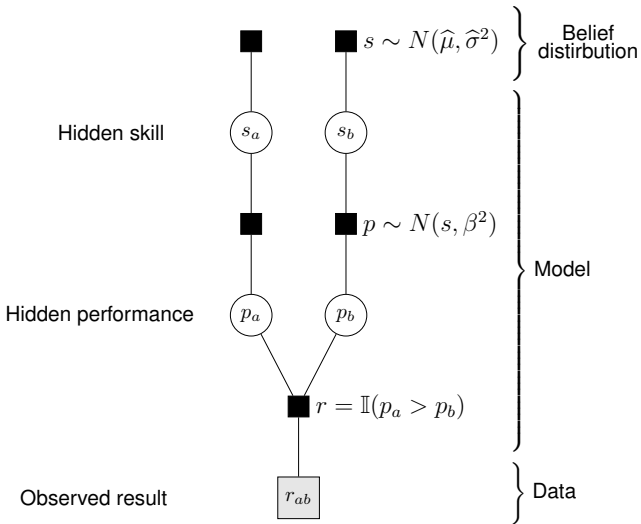
Bayesian skill estimator

How to estimate skill of players?

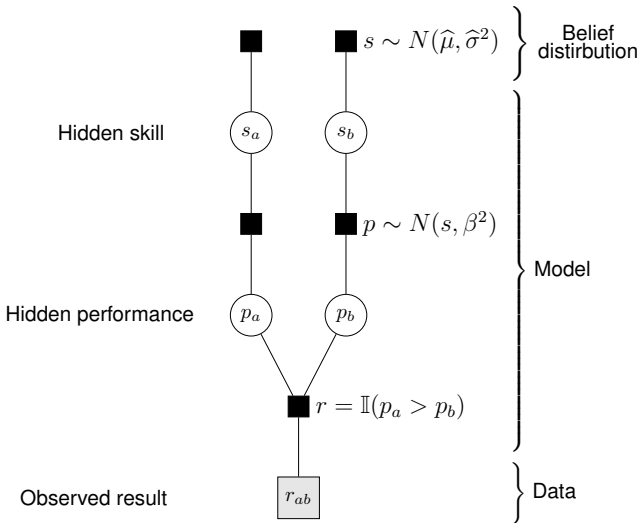


Arpad Elo

Bayesian Elo factor graph



Bayesian Elo factor graph



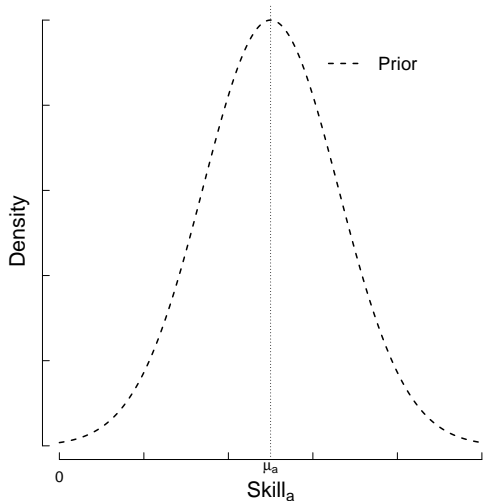
The factor graphs specifies the way to compute the posterior, likelihood, and evidence.

Kschischang FR, Frey BJ, Loeliger HA. Factor graphs and the sum-product algorithm. 2001

$$\overbrace{P(s_a \mid r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a \mid \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a \mid \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}} \quad \text{Win case}$$

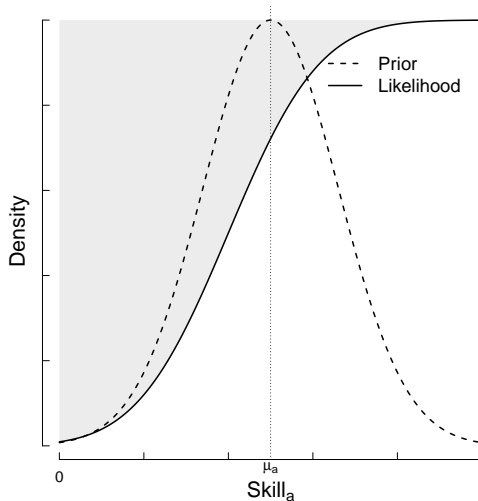
$$\overbrace{P(s_a | r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a | \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a | \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Win case



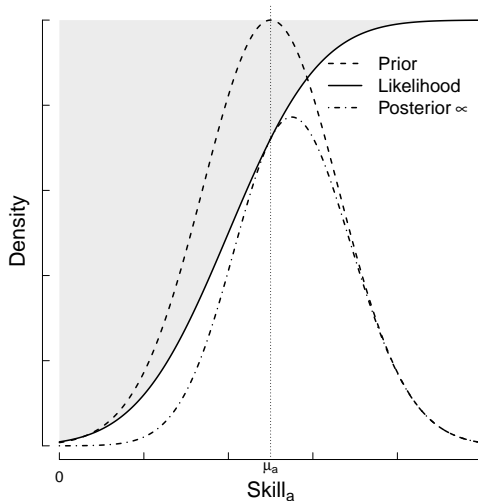
$$\overbrace{P(s_a | r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a | \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a | \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Win case



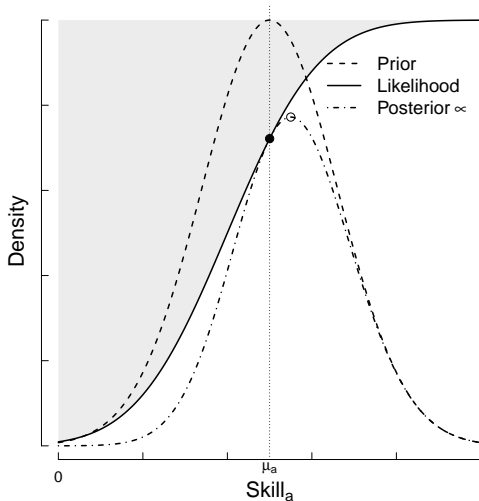
$$\overbrace{P(s_a \mid r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a \mid \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a \mid \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Win case



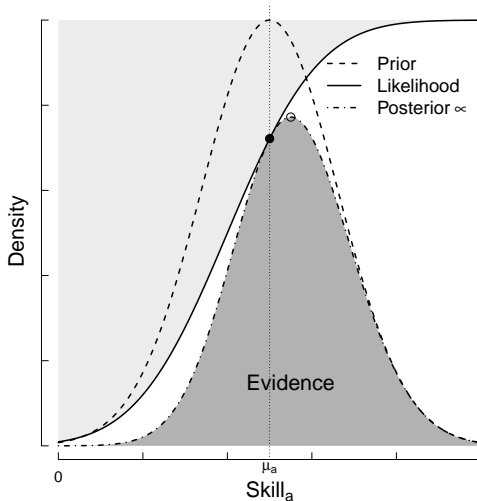
$$\overbrace{P(s_a \mid r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a \mid \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a \mid \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Win case



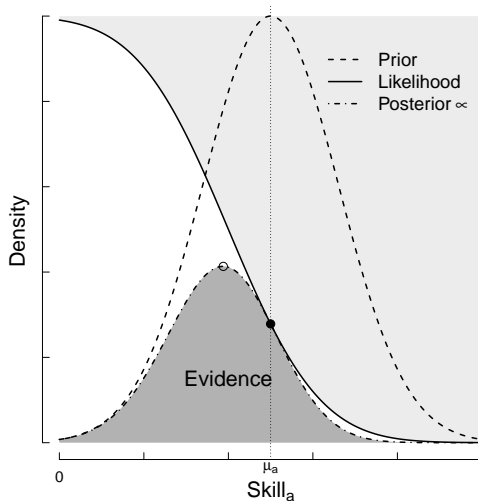
$$\overbrace{P(s_a | r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a | \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{1 - \Phi(s_a | \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Win case



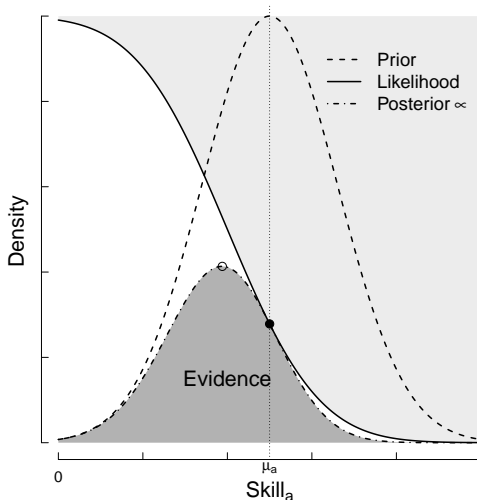
$$\overbrace{P(s_a | r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a | \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{\Phi(s_a | \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Loose case



$$\overbrace{P(s_a | r_{ab}, \text{Elo model})}^{\text{Posterior}} \propto \overbrace{N(s_a | \hat{\mu}_a, \hat{\sigma}_a^2)}^{\text{Prior}} \overbrace{\Phi(s_a | \hat{\mu}_b, 2\beta^2 + \hat{\sigma}_b^2)}^{\text{Likelihood}}$$

Loose case



Bayesian model inference

- Which are our beliefs about different hidden models M ?

Bayesian model inference

- Which are our beliefs about different hidden models M ?

$$P(M_k|D) = \frac{P(D|M_k)P(M_k)}{\sum_{i=1}^n P(D|M_i)P(M_i)}$$

Bayesian model inference

- Which are our beliefs about different hidden models M ?

$$P(M_k|D) = \frac{P(D|M_k)P(M_k)}{\sum_{i=1}^n P(D|M_i)P(M_i)}$$

- To compare models we can compute their ratio probability,

Bayesian model inference

- Which are our beliefs about different hidden models M ?

$$P(M_k|D) = \frac{P(D|M_k)P(M_k)}{\sum_{i=1}^n P(D|M_i)P(M_i)}$$

- To compare models we can compute their ratio probability,

$$\text{Bayes factor}(q, r) = \frac{P(M_q|D)}{P(M_r|D)} = \frac{P(D|M_q)P(M_q)}{P(D|M_r)P(M_r)}$$

Bayesian model inference

- Which are our beliefs about different hidden models M ?

$$P(M_k|D) = \frac{P(D|M_k)P(M_k)}{\sum_{i=1}^n P(D|M_i)P(M_i)}$$

- To compare models we can compute their ratio probability,

$$\begin{aligned} \text{Bayes factor}(q, r) &= \frac{P(M_q|D)}{P(M_r|D)} = \frac{P(D|M_q)P(M_q)}{P(D|M_r)P(M_r)} \\ &= \frac{P(D|M_q)}{\underbrace{P(D|M_r)}_{\text{Evidence!}}} \quad * \text{ With no prior preferences } P(M_q)=P(M_r) \end{aligned}$$

$$P(M_q|D) > P(M_r|D) \stackrel{*}{\iff} P(D|M_q) > P(D|M_r)$$

Bayesian model inference

- Which are our beliefs about different hidden models M ?

$$P(M_k|D) = \frac{P(D|M_k)P(M_k)}{\sum_{i=1}^n P(D|M_i)P(M_i)}$$

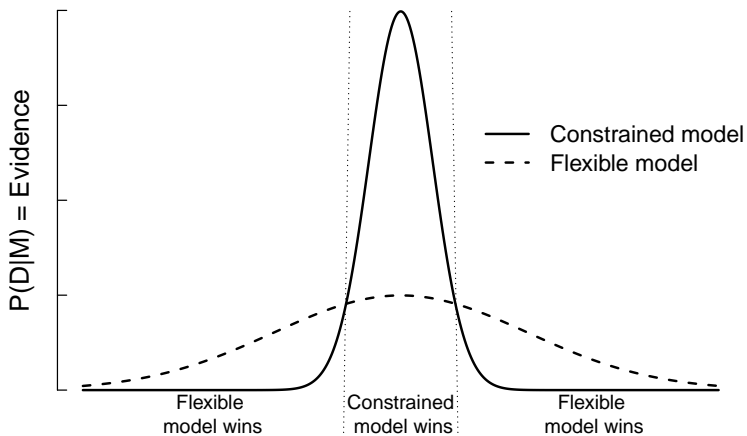
- To compare models we can compute their ratio probability,

$$\begin{aligned} \text{Bayes factor}(q, r) &= \frac{P(M_q|D)}{P(M_r|D)} = \frac{P(D|M_q)P(M_q)}{P(D|M_r)P(M_r)} \\ &= \frac{P(D|M_q)}{\underbrace{P(D|M_r)}_{\text{Evidence!}}} \quad * \text{ With no prior preferences } P(M_q)=P(M_r) \end{aligned}$$

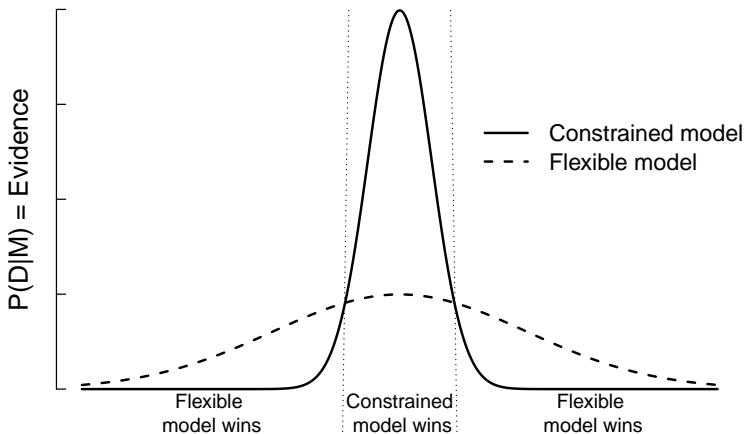
$$P(M_q|D) > P(M_r|D) \overset{*}{\iff} P(D|M_q) > P(D|M_r)$$

All you need is evidence

Evidence

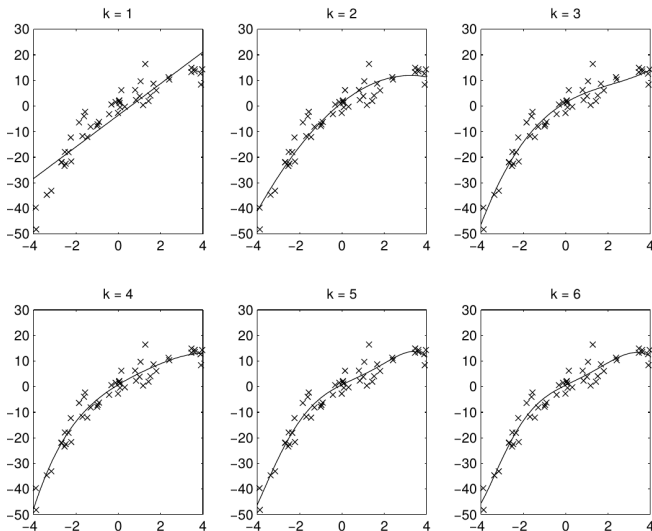


Evidence

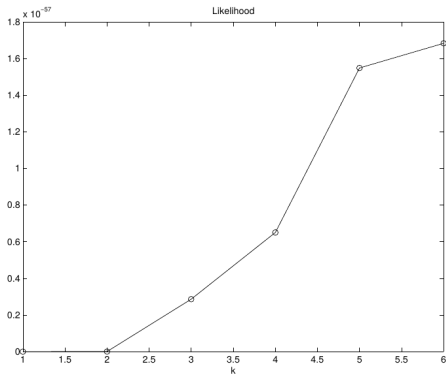
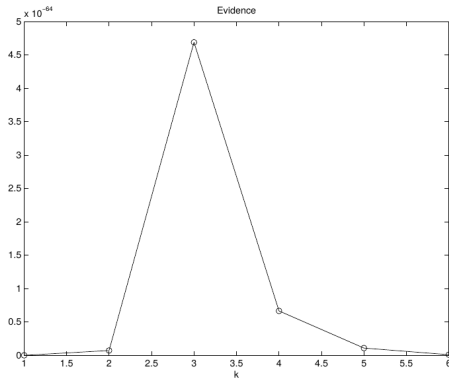


Evidence encode a trade-off between complexity and prediction.

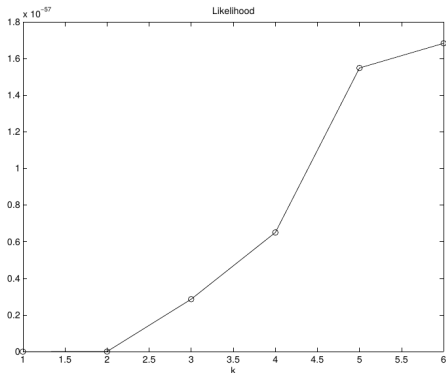
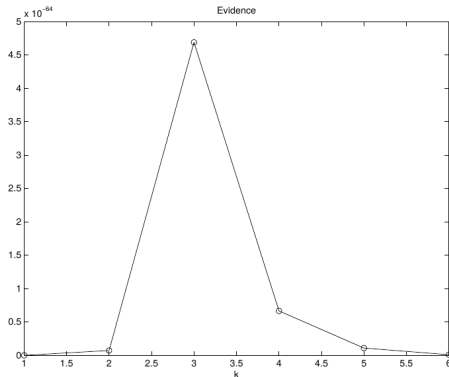
Evidence vs maximum likelihood



Evidence vs maximum likelihood

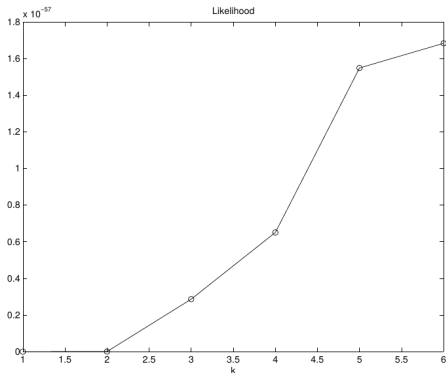
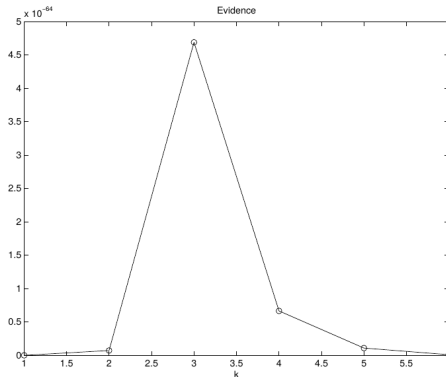


Evidence vs maximum likelihood



With evidence there is no need for regularization

Evidence vs maximum likelihood



With evidence there is no need for regularization

Why evidence is not widely used in machine learning?

Why evidence is not widely used in machine learning?

First let's take a look at Bayesian no-doubt case

Bayesian no-doubt case

Fixed beliefs, even with infinite new data

$$\# \text{Beliefs} = 1 \implies \underbrace{P(B)}_{\text{Prior}} = \underbrace{P(B|D)}_{\text{Posterior}} \quad \begin{array}{l} \forall D \in \text{Data} \\ \forall B \in \text{Beliefs} \end{array}$$

Bayesian no-doubt case

Fixed beliefs, even with infinite new data

$$\# \text{Beliefs} = 1 \implies \underbrace{P(B)}_{\text{Prior}} = \underbrace{P(B|D)}_{\text{Posterior}} \quad \begin{array}{l} \forall D \in \text{Data} \\ \forall B \in \text{Beliefs} \end{array}$$

Likelihood is just the Evidence

$$\# \text{Beliefs} = 1 \iff \text{Likelihood} = \text{Evidence}$$

Who has no doubt? Who has only one belief?

Who has no doubt? Who has only one belief?

- God (if exists)

Who has no doubt? Who has only one belief?

- God (if exists)
- Mathematicians (and other non-empirical sciences)

Who has no doubt? Who has only one belief?

- God (if exists)
- Mathematicians (and other non-empirical sciences)
- Maybe some extremists

Who has no doubt? Who has only one belief?

- God (if exists)
- Mathematicians (and other non-empirical sciences)
- Maybe some extremists
- **All non-bayesian machine learning**

Who has no doubt? Who has only one belief?

- God (if exists)
- Mathematicians (and other non-empirical sciences)
- Maybe some extremists
- **All non-bayesian machine learning** (the hacked-belief approach)

The hacked-belief approach

The best belief after seeing the data
~~maximum likelihood estimator~~ $= \operatorname{argmax}_B P(D|B, M) = \hat{B}$

The hacked-belief approach

The best belief after seeing the data
~~maximum likelihood estimator~~ $= \operatorname{argmax}_B P(D|B, M) = \hat{B}$

$$\text{Hacked evidence} \quad \underbrace{P(D|M)} = \quad \underbrace{\text{Hacked likelihood}} \quad P(D|\hat{B}, M)$$

The hacked-belief approach

The best belief after seeing the data

$$\text{maximum likelihood estimator} = \underset{B}{\operatorname{argmax}} P(D|B, M) = \hat{B}$$

$$\text{Hacked evidence } \underbrace{P(D|M)} = \text{Hacked likelihood } \underbrace{P(D|\hat{B}, M)} = \underbrace{P(D|\underset{\substack{\uparrow \\ B}}{\operatorname{argmax}} P(D|B, M)}, M)}_{\substack{\uparrow \\ \text{Data appears back and forth!!}}}$$

The hacked-belief approach

The best belief after seeing the data

$$\text{maximum likelihood estimator} = \underset{B}{\operatorname{argmax}} P(D|B, M) = \hat{B}$$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}} = \underbrace{P(D|\underset{\substack{\uparrow \\ \text{Data appears back and forth!!}}}{\operatorname{argmax}_B} P(D|B, M)}, M)}_{\text{Maximum likelihood}}$$

Hacked evidence (with MLE) = Maximum likelihood

The hacked-belief approach

The best belief after seeing the data

$$\text{maximum likelihood estimator} = \underset{B}{\operatorname{argmax}} P(D|B, M) = \hat{B}$$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}} = \underbrace{P(D|\underset{\substack{\uparrow \\ \text{Data appears back and forth!}}}{\operatorname{argmax}_B} P(D|B, M)}, M)}_{\text{Maximum likelihood}}$$

Hacked evidence (with MLE) = Maximum likelihood

With great hacked-belief approach comes great overfitting!

With great overfitting comes great regularization!

The best belief after seeing the data
~~maximum a posteriori (estimator)~~ = $\operatorname{argmax}_B P(D|B, M)P(B|M) = \hat{B}$

With great overfitting comes great regularization!

The best belief after seeing the data

$$\text{maximum a posteriori (estimator)} = \underset{B}{\operatorname{argmax}} P(D|B, M)P(B|M) = \hat{B}$$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}}$$

With great overfitting comes great regularization!

The best belief after seeing the data

$$\text{maximum a posteriori (estimator)} = \underset{B}{\operatorname{argmax}} P(D|B, M)P(B|M) = \hat{B}$$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}} = \underbrace{P(D|\underset{B}{\operatorname{argmax}} P(D|B, M)P(B|M), M)}_{\text{Likelihood at maximum a posteriori}}$$

Again data appears back and forth!!

With great overfitting comes great regularization!

The best belief after seeing the data
~~maximum a posteriori (estimator)~~ = $\operatorname{argmax}_B P(D|B, M)P(B|M) = \hat{B}$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}} = \underbrace{P(D|\operatorname{argmax}_B P(D|B, M)P(B|M), M)}_{\text{Likelihood at maximum a posteriori}}$$

\uparrow \uparrow
 Again data appears back and forth!!

Hacked evidence (with MAP) = L2 or L1 regularization

With great overfitting comes great regularization!

The best belief after seeing the data
~~maximum a posteriori (estimator)~~ = $\operatorname{argmax}_B P(D|B, M)P(B|M) = \hat{B}$

$$\underbrace{P(D|M)}_{\text{Hacked evidence}} = \underbrace{P(D|\hat{B}, M)}_{\text{Hacked likelihood}} = \underbrace{P(D|\operatorname{argmax}_B P(D|B, M)P(B|M), M)}_{\text{Likelihood at maximum a posteriori}}$$

\uparrow \uparrow
 Again data appears back and forth!!

Hacked evidence (with MAP) = L2 or L1 regularization

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\overbrace{P(D|M)}^{\text{Evidence}}$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\overbrace{P(D|M)}^{\text{Evidence}} \propto \log P(D|M)$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\overbrace{P(D|M)}^{\text{Evidence}} \propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right)$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\overbrace{P(D|M)}^{\text{Evidence}} \propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M)$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned} \overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\ &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) \end{aligned}$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned}\overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\ &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) = E_p [\log P(D|M)]\end{aligned}$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned}\overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\ &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) = E_p [\log P(D|M)] \\ &= E_p [\log q]\end{aligned}$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned}\overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\ &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) = E_p [\log P(D|M)] \\ &= E_p [\log q] = - \underbrace{H(p, q)}_{\text{Cross entropy}}\end{aligned}$$

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned}\overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\ &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) = E_p [\log P(D|M)] \\ &= E_p [\log q] = - \underbrace{H(p, q)}_{\text{Cross entropy}}\end{aligned}$$

Evidence \propto Cross entropy

Evidence and data science metrics

Is there any data science metrics equivalent to evidence?

$$\begin{aligned}
 \overbrace{P(D|M)}^{\text{Evidence}} &\propto \log P(D|M) = \log \left(\prod_{i=1}^{|D|} P(D_i|M) \right) = \sum_{i=1}^{|D|} \log P(D_i|M) \\
 &\propto \frac{1}{|D|} \sum_{i=1}^{|D|} \log P(D_i|M) = E_p [\log P(D|M)] \\
 &= E_p [\log q] = - \underbrace{H(p, q)}_{\text{Cross entropy}}
 \end{aligned}$$

Evidence \propto Cross entropy
(at validation data set, if hacked-belief approach)